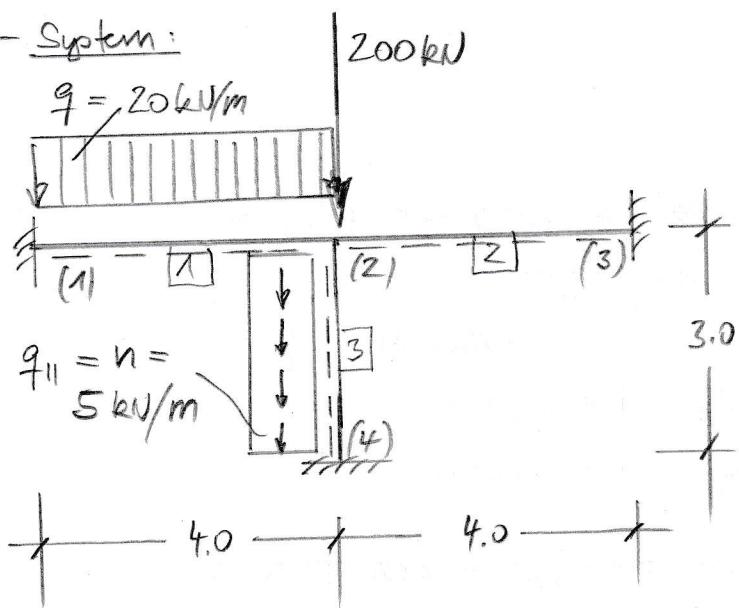


# Übungsbispiel 4: WGV (mit Handrechnung)

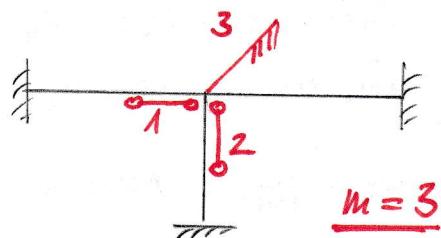
- System:



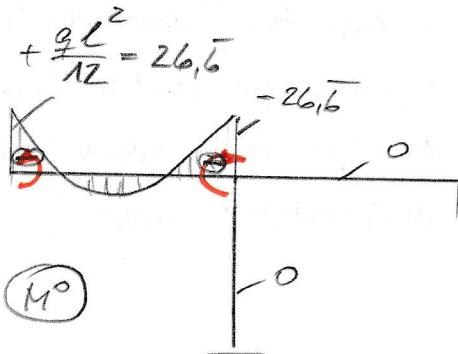
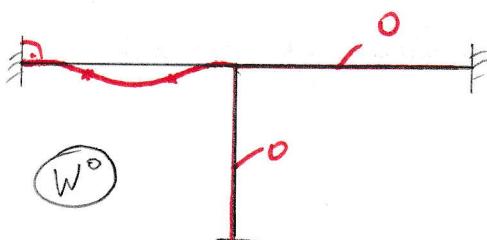
- Initientafel:

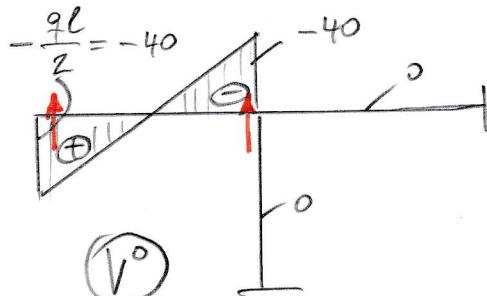
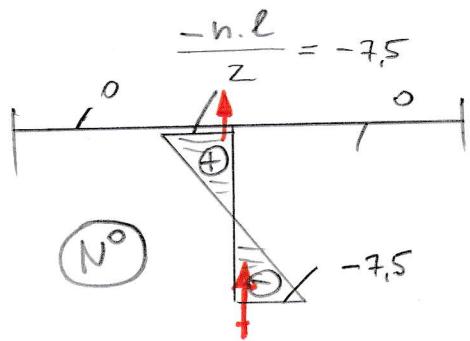
i	a	e	l	B	EJ	EA
1	1	2	4.0	0	4000	100000
2	2	3	4.0	0	6000	100000
3	2	4	3.0	-90°	3000	30000

- Kinem. best. Hauptsystem



- Lastverformungszustand



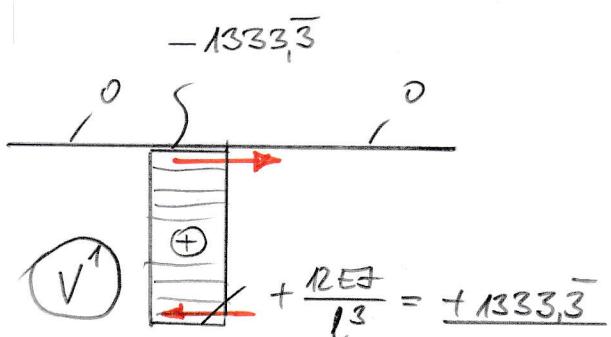
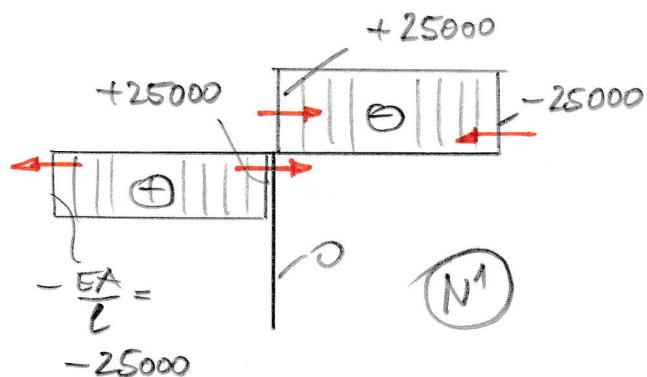
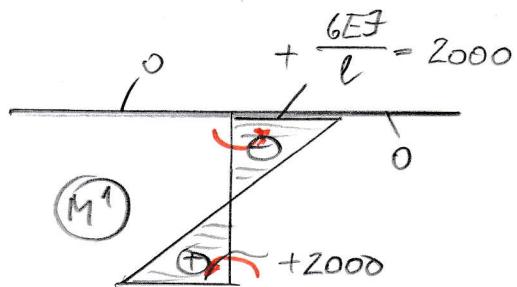
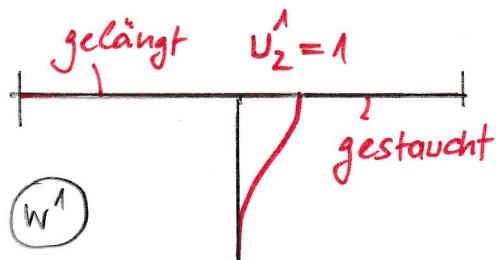


vgl. Schneider 4.1 Tab. 1.1.4

$$(a) \quad (e)$$

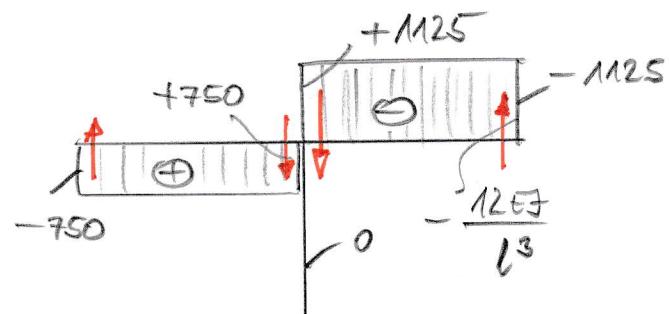
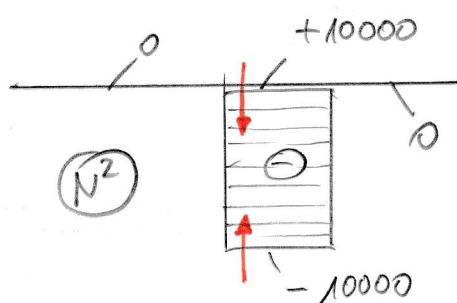
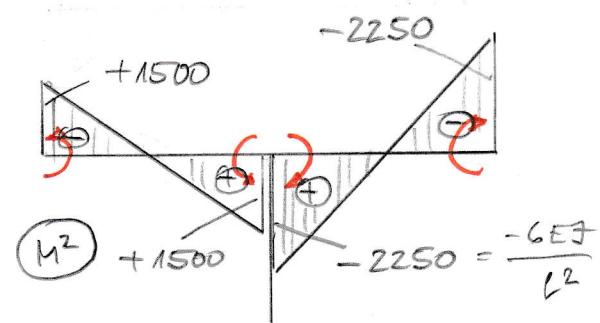
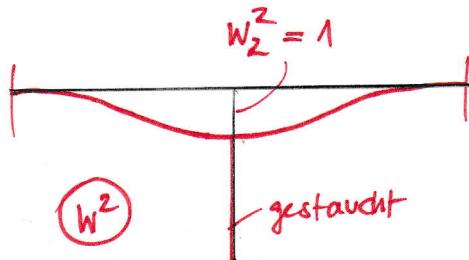
$N_a = -\frac{n \cdot l}{2}$        $N_e = -\frac{n \cdot l}{2}$

- EV21 (Wegfessel am Kn. 2 in horiz. Richtung)

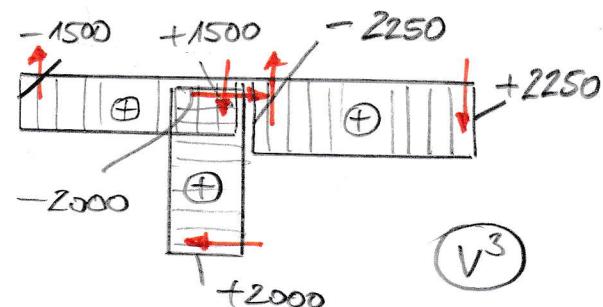
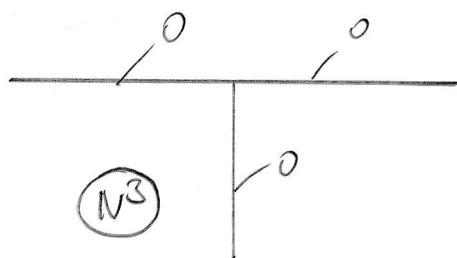
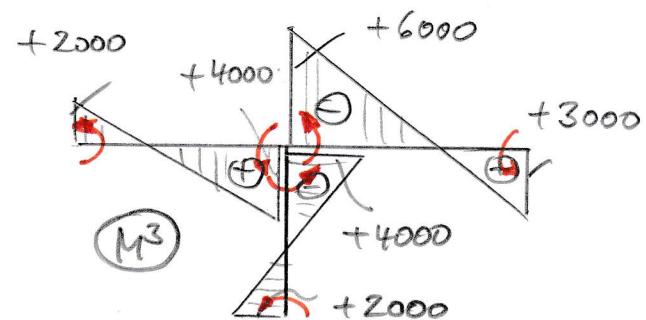
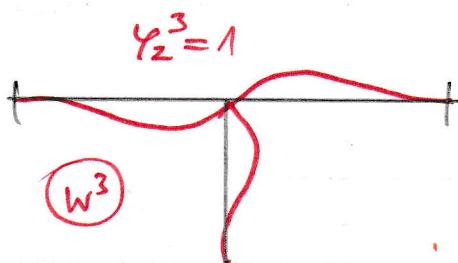


-3-

- EVZ 2: (Wegfessel am Kn. 2 in vertikaler Richt.)



- EVZ 3: (Drehfessel am Kn. 2)



— gleichgewichtsbedingungen ( $m = 3$ )

$$\sum K_{x,2} \stackrel{!}{=} 0 : 0 + y_1(25000 + 25000 + 1333,3) + y_2(0) + y_3(2000) = 0$$

$$\sum K_{z,2} \stackrel{!}{=} 0 : (-200 - 40 - 7,5) + y_1(0) + y_2(10000 + 750 + 1125) + y_3(1500 - 2250) = 0$$

$$\sum M_2 \stackrel{!}{=} 0 : -26,6 + y_1(2000) + y_2(1500 - 2250) + y_3(6000 + 4000 + 4000) = 0$$

→ in Matrizenform:

$$\begin{bmatrix} 51333,3 & 0 & 2000 \\ 0 & 11875 & -750 \\ 2000 & -750 & 14000 \end{bmatrix} \cdot \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 247,5 \\ 26,6 \end{bmatrix}$$

— Lösung und Superposition  $\underline{z} = z^0 + \sum_{i=1}^3 y_i \cdot z^i$

Lösung des Gleichungssystems  $[K] \cdot [y] = [r]$

$[K]$ = Steifigkeitsmatrix (pos. Definit + symmetrisch)		
51333,333	0,000	2000,000
0,000	11875,000	-750,000
2000,000	-750,000	14000,000

$[r]$ = Lastvektor (rechte Seite)
0,000
247,500
26,667

$[K]^{-1}$ = Inverse Steifigkeitsmatrix		
1,959E-05	-1,774E-07	-2,808E-06
-1,774E-07	8,450E-05	4,552E-06
-2,808E-06	4,552E-06	7,207E-05

$[y]$ = Lösungsvektor	entspricht:
-1,188E-04	$u_2$
2,103E-02	$w_2$
3,049E-03	$\phi_2$

### Nachlaufrechnung (Superposition)

mit Hilfe einer einfachen Matrizenmultiplikation

Stabend- (Vorzeichen nach WGV)  
schnittgrößen

	am LVZ	am EVZ1	am EVZ2	am EVZ3
M <sub>1,rechts</sub>	26,667	0,000	1500,000	2000,000
M <sub>2,links</sub>	-26,667	0,000	1500,000	4000,000
M <sub>2,rechts</sub>	0,000	0,000	-2250,000	6000,000
M <sub>3,links</sub>	0,000	0,000	-2250,000	3000,000
M <sub>2,unten</sub>	0,000	2000,000	0,000	4000,000
M <sub>4,oben</sub>	0,000	2000,000	0,000	2000,000

1,000000
-0,000119
0,021035
0,003049

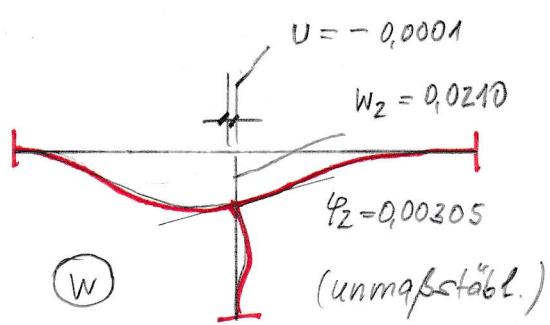
nach Baustatik
-64,316
17,080
-29,036
-38,182
11,957
5,860

	am LVZ	am EVZ1	am EVZ2	am EVZ3
V <sub>1,rechts</sub>	-40,000	0,000	-750,000	-1500,000
V <sub>2,links</sub>	-40,000	0,000	750,000	1500,000
V <sub>2,rechts</sub>	0,000	0,000	1125,000	-2250,000
V <sub>3,links</sub>	0,000	0,000	-1125,000	2250,000
V <sub>2,unten</sub>	0,000	-1333,333	0,000	-2000,000
V <sub>4,oben</sub>	0,000	1333,333	0,000	2000,000

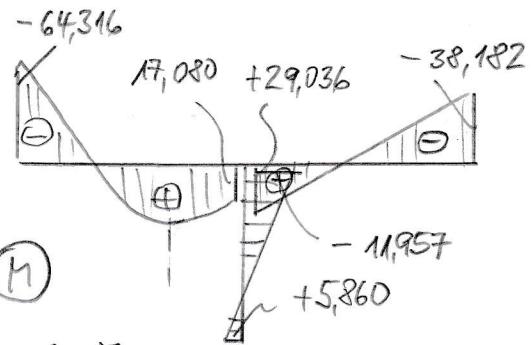
nach Baustatik
-60,349
-19,651
16,805
-16,805
-5,939
5,939

	am LVZ	am EVZ1	am EVZ2	am EVZ3
N <sub>1,rechts</sub>	0,000	-25000,000	0,000	0,000
N <sub>2,links</sub>	0,000	25000,000	0,000	0,000
N <sub>2,rechts</sub>	0,000	25000,000	0,000	0,000
N <sub>3,links</sub>	0,000	-25000,000	0,000	0,000
N <sub>2,unten</sub>	-7,500	0,000	10000,000	0,000
N <sub>4,oben</sub>	-7,500	0,000	-10000,000	0,000

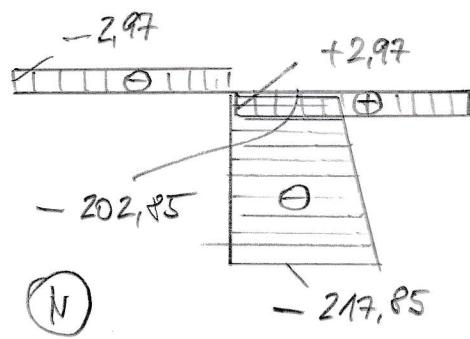
nach Baustatik
2,969
-2,969
-2,969
2,969
202,846
-217,846



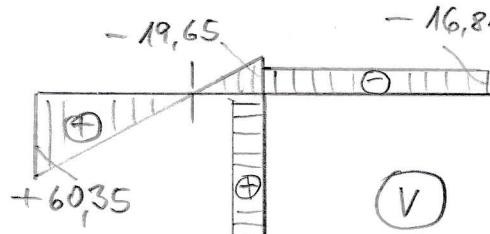
Kontrolle



$$17,080 \xrightarrow{-} 29,036 \\ \xleftarrow{+} 11,957$$



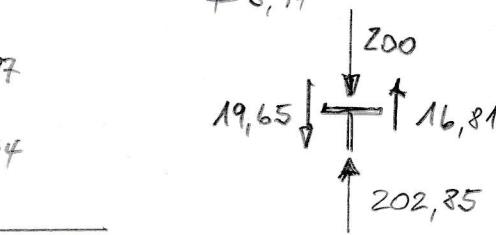
(1)



(2)

$$\checkmark \rightarrow \begin{array}{c} 2,97 \\ (2) \\ 2,97 \end{array} \rightarrow \begin{array}{c} 5,94 \end{array}$$

Kontrolle:  
am Knoten Z



(3)